

Mass Measurement with the DMS500

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Why Mass Measurement from Spectral Data?



Why mass:

- Gravimetric measurements are the basis of current legislation and historical environmental data.
- With differences in particle sizing standards (DMA mobility classification / aerodynamic sizing / DMS electrical mobility classification), particle mass is unambiguously defined.
- Why from a spectral instrument:
- Improved sensitivity vs gravimetric methods
- Real-time data
- Measurement and differentiation of accumulation mode for unfiltered / partial filtered vehicles and DPF efficiency along with nucleation mode comprising the majority of mass emissions from DPF equipped vehicles.

Mass calculation from number:size data



• Measurement of concentration and size allows calculation of particulate mass.

Mass Weighting Size:Number Spectra



- Sensitivity to calibration
 - If mass ~ diameter³, then 10% size error \Rightarrow 30% mass error
 - solved with traceable calibration via PSL spheres
- Noise in large particle sizes amplified by mass weighting
- Effect of spectral broadening
- Particle density
 - effective density varies with particle size
 - different for nucleation & accumulation modes
 - 'diameter' not well defined for agglomerates



Effect of mass weighting on noise

Mass Weighted number: size spectra



Particle diameter, nm

Effect of Spectral Broadening



Variable Particle Density



- Nucleation mode & accumulation obviously different.
- Accumulation variation demonstrated by various studies (DMA/APM, DMA/ELPI etc)
- for example, APM data (Park, Kittelson, McMurray):

Accumulation mode density



[†] Environ Sci. Technology **37** 577–583 (2003)

Solution: Lognormal mode identification



- DMS normally produces up to 41 channels of size data
- Mode identification software can reduce this to just 6 for engine aerosol:

Nucleation			Accumulation		
GMD	GSD	N/cc	GMD	GSD	conc

$$df = \frac{1}{\sqrt{2\pi}\log\sigma_g} \exp\left[-\frac{\left(\log CMD - \log D_p\right)^2}{2\log^2\sigma_g}\right] d\log D_p$$

- The nucleation and accumulation modes can then be considered separately. Factoring in air mass flow (and λ) gives total mass
- Software identifies if a mode is 'real' relative to the noise base of the instrument, and if not discard it
- Reduces noise related error in mass estimation, especially in 'tail' of accumulation mode
- Removes cross sensitivity introduced by crude size cut-off methods
- Improves spectral resolution

Bayes' Theorem:

Posterior Probability ∞ Prior Probability \times Likelihood P(w|J) ∞ P(w) \times P(J|w)

- Prior: Assumptions about size and width of aerosol modes, gives *soft* limits on fit
- Likelihood: Probability of the data (**J**, ring currents) given some lognormal parameters (**w**).
- Posterior: The fit criterion, to be maximised

To fit:

- 1. Guess set of parameters and generate lognormal spectrum
- 2. Get ring currents for spectrum from transfer function
- 3. Compare these with measured ring currents, calculate likelihood (next slide)
- 4. Calculate Posterior from Likelihood and preset Prior
- 5. Iterate $1 \rightarrow 4$ to maximise Posterior



Likelihood Calculation

- Noise on electrometer rings measured during zero — gives expected standard deviation (σ) of guessed currents (i) from measured currents (j)
- Likelihood per ring:

$$P(j \mid i, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(j-i)^2}{2\sigma^2}\right)$$

 Assume independent probabilities, ∴ total Likelihood for 22 rings:

$$P(\mathbf{J} \mid \mathbf{w}) = \prod_{k=1}^{22} \frac{1}{\sigma_k \sqrt{2\pi}} \exp\left[-\frac{(j_k - i_k(\mathbf{w}))^2}{2\sigma_k^2}\right]$$





Example Diesel Engine Prior





How many modes?



• Let $P(H_m | \mathbf{J})$ be the probability that there are truly *m* Lognormal modes, given the measured ring currents **J**. Then by Bayes' theorem:

$$P(H_m | \mathbf{J}) \propto P(H_m) P(\mathbf{J} | H_m)$$

Marginalisation rule : $P(X | I) = \int_{-\infty}^{\infty} P(X, Y | I) dY$
$$\Rightarrow P(\mathbf{J} | H_m) = \int \cdots \int P(\mathbf{J}, \mathbf{w} | H_m) d^m \mathbf{w} \qquad (1)$$

Product Rule : $P(Y, X | I) = P(Y | X, I) P(X | I)$
$$\Rightarrow P(\mathbf{J}, \mathbf{w} | H_m) = P(\mathbf{J} | \mathbf{w}, H_m) P(\mathbf{w} | H_m) \qquad (2)$$

- We assume that the prior probability of *m* modes, $P(H_m)$, is uniform
- Equation (2) is now just the product of our original likelihood and prior, but now evaluated for a specific number of lognormals, i.e. the product of the likelihood of the overall spectrum and all the individual priors.
- (2) is substituted into (1) and evaluated. This takes considerable PC power in real-time!

Automatic mode identification on NEDC





Time / s

Real-time Implementation

- Integrated into instrument interface
- Modes displayed in real-time along with conventional spectrum
- Summary parameters (size, concentration, σ_g) logged and available as analogue output signals
- Mass calculated and displayed, logged or available as analogue output.





Lognormal Data Processing: Reduced Noise



Lognormal Data Processing: Better Resolution



• CAMBUSTION •

Dp (nm)

(Different Priors used to those for Diesel Engines!)

Density Function - SMPS



- Based upon work by Park, Cao, Kittleson and McMurry[†]
- Related DMA diameter to mass for heavy duty diesel via an effective density by cutting with Aerosol Particle Mass Analyser (APM)
- Recently shown to also apply to light duty diesel[‡]

Accumulation mode mass



[‡] J.S. Olfert *et al.* in preparation

Accumulation Mode Size



What size is this?



- DMS Calibrated with PSL Spheres
- Compare SMPS (mobility) sizing with DMS (electrical mobility) sizing for Diesel Agglomerates



DMA:DMS Diameter Relationship – Diesel Agglomerates



New DMS Mass Weighting Rule





New DMS Mass Weighting Rule



DMS Diameter to Mass Relationship



Mass Estimation from DMS500



Summary – DMS500 Mass Calculation



- Lognormal mode identification
 - reduces large particle noise by data redundancy
 - discriminates between nucleation & accumulation modes to calculate soot mass, or apply different density laws.
 - takes into account spectral blurring in instrument to correctly resolve mode widths.
 - reduces amount of data to be handled by users
 - allows nucleation mode to be measured and ignored at will, from one test.
- Mass weighting of particulate modes
 - mass : diameter relationship derived from DMA literature, but modified due to different charge : drag ratio sizing basis.

Validating Mass Measurements



- Correlation is very easy to demonstrate:
 - most instruments (not CPC!) are linear with increasing concentration, so just test at a variety of concentrations with similar aerosols
 - even easier, test over different periods of emission.
- Neither of these give useful validation
 - must ensure a variety of particle sizes in validation data set
 - data presented here covers peaks between about 60nm and 140nm mobility diameter for different steady state conditions.
 - confidence improved by agreement with a priori calculation, rather than just a posterior correlation

DPF Mass Correlation Validation



- Production vehicle (2.21 common rail) with DPF on chassis rolls and 2.01 common rail engine with prototype calibration on engine dyno.
- Measurements taken both by DPF weighing and filter paper measurement.
- Steady state test points selected for validation over maximum particulate size range.
- NEDC cycle mass for real application validation
- DMS500 sample drawn from pre-DPF flow via built-in dilution system and heated line.
- Mass flow calculated from intake MAF and exhaust lambda logged to DMS500 auxiliary analogue inputs.



- NEDCs (sometimes inc EUDCs), warm and cold start
- 100 kph (5th gear), 70 (4th/5th), 32 (2nd) cruises
- 1500 rpm @ 190, 650, 700 nm
- Fixed speed/load points on engine dyno
- DPF weighings (DMS primary + secondary dilution, heated line)
- Filter Paper in CVS Tunnel (DMS secondary dilution)

DMS500 Built-in 2 Stage Dilution





Vehicle Tests: Mass Conc. over NEDC



DMS Mass Test Results



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Tunnel Mass Conc by Filter or Exhaust Mass Conc by DPF / μ g / cc

Conclusions



- Mass calculation from spectral data allows correlation with gravimetric measurements and standards.
- Issues with mass calculation accuracy include size calibration, large particle noise floor and variable density.
- Mode identification reduces noise floor, improves size distribution accuracy and allows discrimination between nucleation and accumulation modes
- Variable particle density model modified for DMS size response
- Mass measurement validated on two drivetrains, against DPF and filter papers weights.
- Agreement with DPF soot mass within 10%
- Approximate 10% underestimate compared with filter paper weighings: assumed due to gas phase adsorption onto filter paper.